User's Manual

W500T – W500TMB

CE

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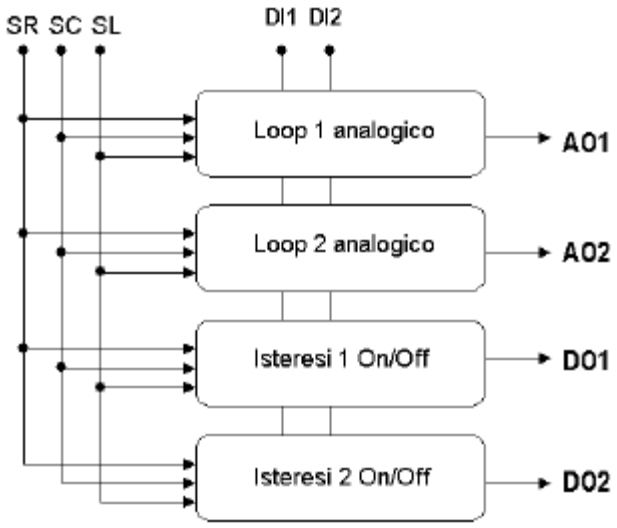
INTRODUCTION

The controller is provided with four control Loops, two Analogue Loop and two on/off Hysteresis Loops.
Each Analogue Loop is connected to a 0-10 Vdc output.
Each on/off hysteresis is linked to a relay output with exchange contact. All Loops have independent control parameters and set point.
All the four Loops share the three sensors: Control Sensor **SR**, Compensation Sensor **SC** and Limit Sensor **SL**. The Control Sensor is compulsory while the Limit Sensor and Compensation Sensor can be omitted. If the Compensation Sensors and/or the Limit Sensor are present, it is possible to enable the relevant functions. The device is also equipped with two dry-contact digital inputs, which can be used for outside enable or summer/winter changeover functions

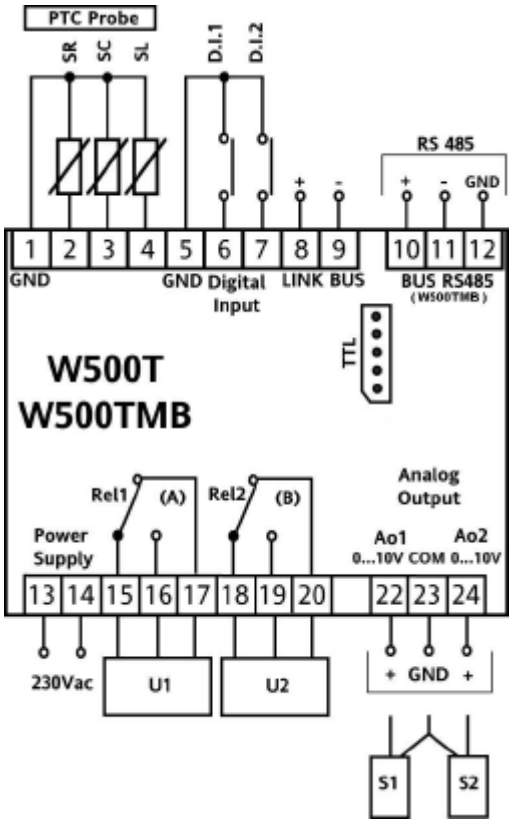


The device is characterized by a user interface composed of a 3 ½-digit FND display, five buttons and of twelve LEDs located on the front membrane. The information displayed on screen depends on whether the sensors are present or not and on the related function enable.

The controller is also provided with a two-wire local bus called Link Bus. Through the local bus port it is possible to connect up to 4 different devices with the purpose to share the three Sensors and the operating mode with other devices of the same line. The local bus also allows the W500T to be supervised, if at least one W500TMB is connected.
The W500TMB version distinguishes from the basic W500T for its on-board RS485-Modbus communication interface and for the Real Time Clock with daily and weekly schedules.
The W500TMB allows supervision also for other W500T devices (max. n. 3) connected to it through a Link Bus and the set time schedules can be shared.

Electrical connections:

1	**GND**		**13**	**230 Vac F**
2	**SR**		**14**	**230 Vac N**
3	**SC**		**15**	**Rel 1 CO**
4	**SL**		**16**	**Rel 1 NA**
5	**GND**		**17**	**Rel 1 NC**
6	**Di1**		**18**	**Rel 2 CO**
7	**Di2**		**19**	**Rel 2 NA**
8	**Link Bus +**		**20**	**Rel 2 NC**
9	**Link Bus -**		**22**	**Ao1**
10	**Bus 485 +**	**W500TMB only**	**23**	**GND**
11	**Bus 485 –**		**24**	**Ao2**
12	**GND 485**			



Legend:
SR: Control sensor
SC: Compensation sensor
SL: Limit sensor
U1: User 1 (e.g. fan or damper)
U2: User 2 (e.g. on/off valve or circulation pump)
S1: Proportional actuator 0 – 10 Volt
S2: Proportional actuator 0 – 10 Volt

USER INTERFACE

The device is characterized by a user interface composed of a 3 ½-digit FND display, five keys and of twelve LEDs located on the front membrane. The information displayed on screen depends on whether the sensors are present or not and on the related function enable. Using the buttons it is possible to navigate a cascade menu, which allows configuring individually the functions to be assigned to the 4 independent outputs.

Description of keys

Button **Up** to increase values. Used both for parameter modification and for moving inside the menus.

Button **Down** to decrease values. Used both for parameter modification and for moving inside the menus.

Esc — Cancel and menu exit

Set — Parameter programming and confirmation

Ovr — Operating mode override

Description of Led

Ao1	Led associated to analogue output 1, it is on during data display.
Ao2	Led associated to analogue output 2, it is on during data display.
SR	Led associated to control sensor, it is on during data display.
SL	Led associated to limit sensor, it is on during data display.
SC	Led associated to compensation sensor, it is on during data display.
DI1	Led associated to digital input 1, it is on when the input is active (closed contact).
DI2	Led associated to digital input 2, it is on when the input is active (closed contact).
Rel1	Led associated to relay output 1, it is on when the output is active.
Rel2	Led associated to relay output 2, it is on when the output is active.
ⓘ	Led associated to anomaly signal.
Ovr	Led associated to override status of the *Operating Mode*
Mode	Led associated to *Operating Mode*. On — Comfort Blinking — Reduced Off — Stop

FUNCTION DESCRIPTION

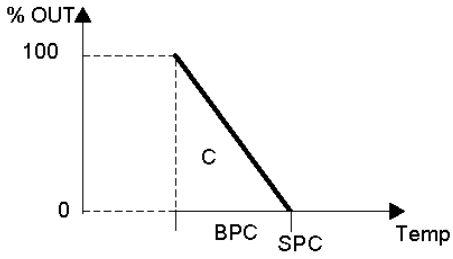
GENERAL

First of all it is necessary to define the OPERATING MODE for each one of the four Control Loops. The Operating Mode constitutes the functioning type to be assigned to a specific output. Heating control means that the output moves in an inversely proportional way with respect to the value measured by the **Control Sensor**, vice versa is the meaning of cooling control.

FOR THE 2 ANALOGUE OUTPUTS CAN BE SELECTED:

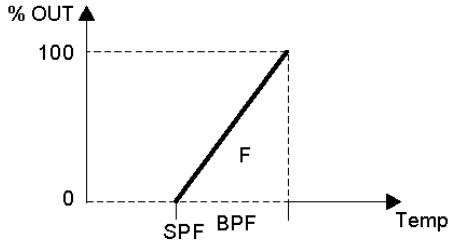
MODE 1A: HEATING LOOP

If the output value must increase, while the Control Sensor value goes below the Operating Set. When the set point is achieved the output is zero. If the control Temperature goes below the **Heating Set Point** value (SPC) minus the **Heating Proportional Band** (BPC) the relevant analogue output goes to 100%, equivalent to10 Vdc.



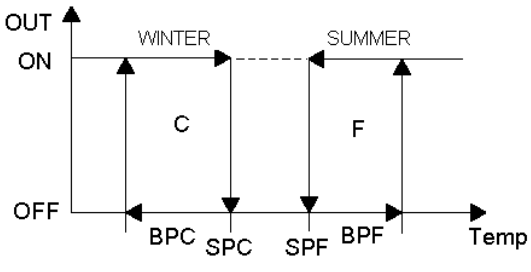
MODE 2A: COOLING LOOP

If the output value must increase, while the Control Sensor value goes above the Operating Set. When the set point is achieved the output is zero. If the control Temperature goes above the **Cooling Set Point** value (SPF) plus the **Cooling Proportional Band** (BPF) the relevant analogue output goes to 100% equivalent to 10 Vdc.



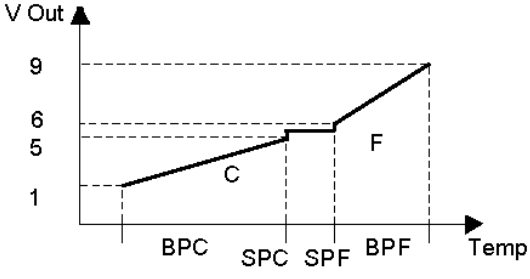
MODE 3A: HEATING / COOLING LOOP FROM S/W CHANGEOVER

If the Heating or Cooling Loop is enabled through the contact input (D.i.2) in order to carry out a season changeover. When the D.i.2 contact is open, the Loop passes to "Heating" control type, under closed contact the Loop passes to "Cooling" control type. The two "Set" (SPC, SPF) and the two proportional bands (BPC, BPF) are independent.



MODE 4A: HEATING LOOP / COOLING IN SEQUENCE

If it is required to exploit the 1-5 6-9 V control characteristic of CONTROLLI actuators to realize a Heating Cooling sequence with a unique 0–10 Vdc analogue output. When the set point is achieved the output is 5,5 Vdc. If the control Temperature goes below the **Heating Set Point** value (SPC) minus **Heating Proportional Band** (BPC), the relevant analogue output goes to 1 Vdc. If the control Temperature goes above the value the **Cooling Set Point** value (SPF) plus **Cooling Proportional Band** (BPF) the relevant analogue output goes to 9 Vdc.

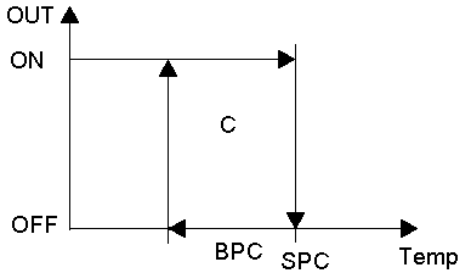


In this case, if a heating-Cooling sequence is required, the two actuators must be connected n parallel to the same output selecting the range 1 – 5 Vdc with reverse action for the actuator, which manages the heating channel, while for the actuator managing the Cooling channel, it is necessary to select the range 6 – 9 Vdc with direct action.

FOR THE 2 ON/OFF DIGITAL RELAY OUTPUTS CAN BE SELECTED:

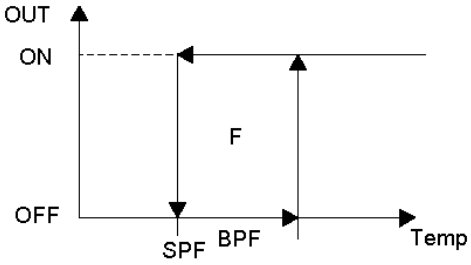
MODE 1D: ON/OFF HEATING HYSTERESIS

If the output value must turn to ON when the value of the Control Sensor goes below the Operating Set minus the Hysteresis band. When the set point is achieved, the relay output is in OFF status.



MODE 2D: ON/OFF COOLING HYSTERESIS

If the output value must turn to ON when the value of the Control Sensor goes above the Operating Set plus the Hysteresis band. When the set point is achieved, the relay output is in OFF status.

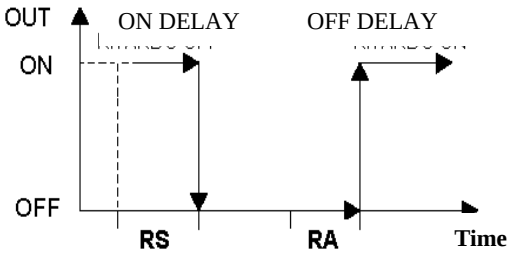


MODE 3D: HEATING / COOLING HYSTERESIS FROM S/W CHANGEOVER

If it is required to enable the heating or cooling hysteresis through the contact input (D.i.2) to carry out a season changeover. When the D.i.2 contact is open, the Loop passes to "Heating" control type, under closed contact the Loop passes to "Cooling" control type. The two "Set" (SPC, SPF) and the two proportional bands (BPC, BPF) are independent.

MODE 4D: ON/OFF DELAY

If it is required to enable or disable a relay output with a specified delay at stop and/or start. The delay is considered with respect to an event, which can be:



- Operating Mode (NM and RF => ON, FA => OFF), if a stop and/or start delay of a device following the Operating Mode is required.
- The status of one of the two digital inputs (D.i.1 or D.i.2), if it is required a stop and/or start delay of a device following the status of one or both dry contact inputs.
- The status of the other Relay output, if it is required a stop and/or start delay of a device following the status of the other digital relay output.

The ON Delay (**RA)** and the Off Delay (**RS**) can be set individually in seconds.
The events generating the changeover are according to an "OR" logic, which means that, if more than one event condition is enabled, it is sufficient that only one is true.
The maximum allowed delay is 60 minutes.

For all Set point and Band parameter settings, see page 16.

CONTROL TYPE

Once the OPERATING MODE is stated, it is necessary to set the CONTROL TYPE, i.e. the control criteria used by the OPERATING MODE. The control type can be:

- Proportional or Proportional + Integral (P or P+I)
- With fixed operation set point or compensated in function of **C**ompensation **S**ensor.
- With or without minimum and/or maximum limit in function of **L**imit **S**ensor.

At this point, to improve the device understanding, it is necessary to recall some basic concepts about the used control type used.

PROPORTIONAL CONTROL (P)

Given a SET POINT (required value), the difference between this value and the VALUE detected by the **C**ontrol **S**ensor is called ERROR.

A proportional control is obtained when the value of a controller output moves proportionally to the ERROR. The PROPORTIONAL BAND determines the quantity of the action (gain) in function of ERROR. When the ERROR is equal to the PROPORTIONAL BAND the output value is equal to 100 %.
Setting a too small PROPORTIONAL BAND can generate oscillation phenomena of the output. Setting an excessively wide PROPORTIONAL BAND can generate a change from the SET of the controlled temperature.

PROPORTIONAL CONTROL + INTEGRAL (P+I)

If to **P** action is added an **I** action, the result is a more accurate control, which takes into account the error variation in time. It is necessary to define an INTEGRATION TIME, which states the time, after which the Proportional action is restored. Generally, INTEGRAL action is necessary when the PROPORTIONAL BAND allows a variation, conferring to the INTEGRAL action the task to cancel the remaining error.

The two 0-10 Vdc analogue outputs can be P or P+I, therefore, the parameters to be set for each output will be:

- SET POINT (with fixed-point control)
- PROPORTIONAL BAND
- INTEGRATION TIME (if I action is enabled)

The 2 relay outputs can be only P, the parameters to be set will be:

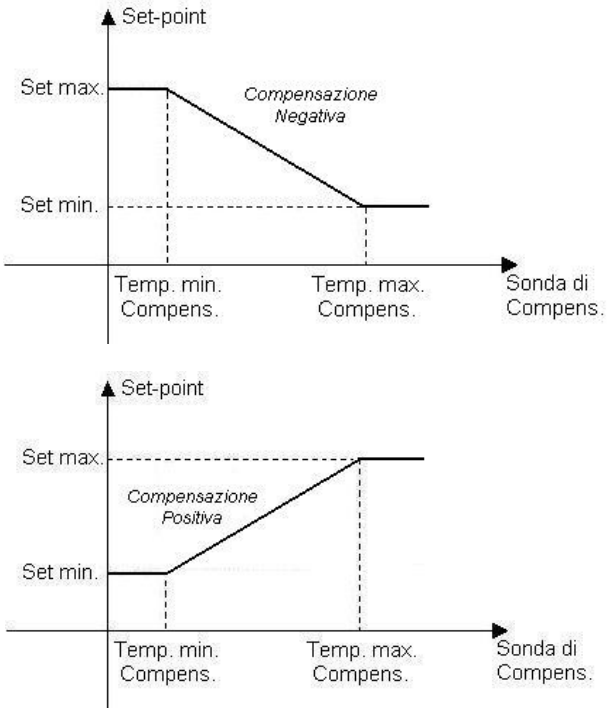
- SET POINT (with fixed-point control)
- HYSTERESIS BAND

The Control Sensor used is the one connected to **SR** terminal, if not differently specified ("SR sharing" see paragraph related to Link Bus). If the control sensor is not connected correctly to **SR** terminal or is not shared correctly with other devices the Anomaly led ⓘ lights up**.**

In the OPERATING MODE 4D, the relay output behaves as a timed sequencer and it controls in function of time events and not in function of temperature.

See page 21 to set the Operating Modes and control types.

SET-POINT COMPENSATION



The operation SET POINT can be fixed or determined by a compensation curve in function of the value read by the relevant sensor. The compensation curve is a broken line passing between two points defined by four values. In function of the value read by the Sensor, a SET-POINT value in a range between a minimum and a maximum will be defined. *Negative Compensation* occurs when the Operation Set-point increases while the value measured by the compensation sensor decreases. *Positive Compensation* occurs when the Operation Set-point increases while the value of the **C**ompensation **S**ensor increases. It is possible to set both Negative and Positive Compensations both for heating and for cooling control Loop.
Each Operation Set-point value, both in heating and cooling control Loop, can be associated to its own compensation curve expressed by a value pair:

- SET-POINT 1 corresponding to TEMPERATURE 1
- SET-POINT 2 corresponding to TEMPERATURE 2

If the Compensation Sensor is present and the Compensation of an Operating Mode is enabled, it is necessary to determine the four values of the curve. Such values become eight in case of Operating Mode 3A, 4A and 3D because it is necessary to set a compensation both for the heating and for the cooling loops. In the latter case, if compensation should be disabled for only one of the two Loops, it is necessary to set the minimum Set-point equal to the maximum value achieving a fixed operation Set-point. It is not possible to enable compensation in Operating Mode 4D.
The Compensation Sensor used is the one connected to **SC** input, if not differently specified ("SC sharing" see paragraph related to Link Bus). To enable Compensation first connect or share the **C**ompensation **S**ensor. If compensation is enabled on any Operating Mode and the **C**ompensation **S**ensor is not connected correctly to **SC** terminal or is not shared correctly with other devices, the Anomaly led ⓘ lights up and the control Set-point becomes the value set for fixed point, i.e. without Compensation.
For all compensation parameters settings see page 16.

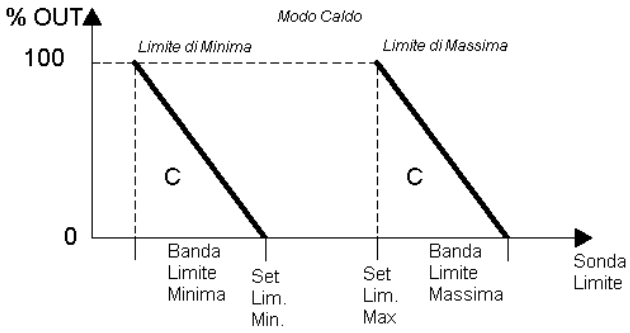
MINIMUM AND/OR MAXIMUM LIMITS

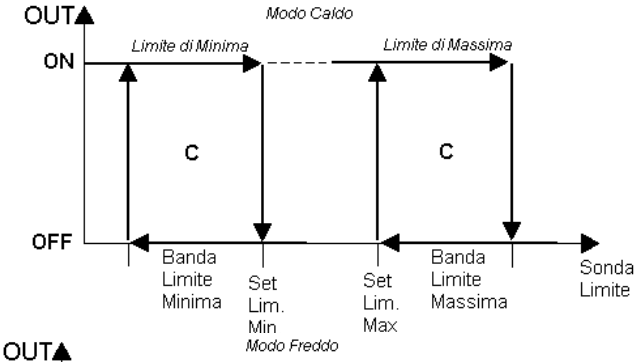
Limit Loops are P-type only and always operate with fixed Set point. If enabled, they work in parallel to the control Loop. For each Operating Mode (except Mode 4D) the minimum and/or maximum limits are enabled individually. In presence of active Limits, the output values will be determined by the set parameters. For each control Loop 4 settings are possible:

- Disabled limits
- Minimum limit enabled
- Maximum limit enabled
- Minimum and a maximum limit enabled

The behaviour of a limit Loop output will be different if the Loop is in heating or cooling Mode. For 3A, 4A and 3D operating Modes, it will be possible to enable the minimum and/or maximum limits both for heating and cooling Mode.

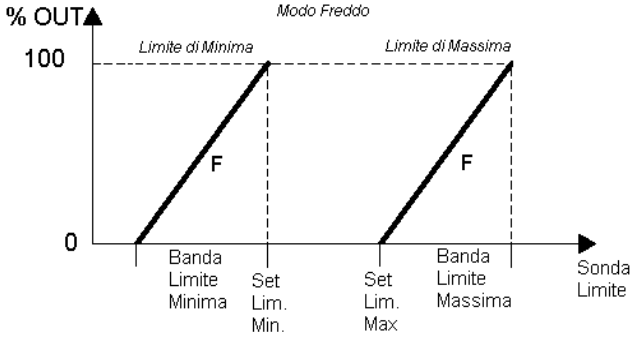
The term “Minimum limit” indicates a function intended to avoid that the temperature measured by the Limit Sensor SL ***goes below*** the specified values.
The term “Maximum limit” indicates a function intended to avoid that the temperature measured by the Limit Sensor SL ***overcomes*** the specified values.

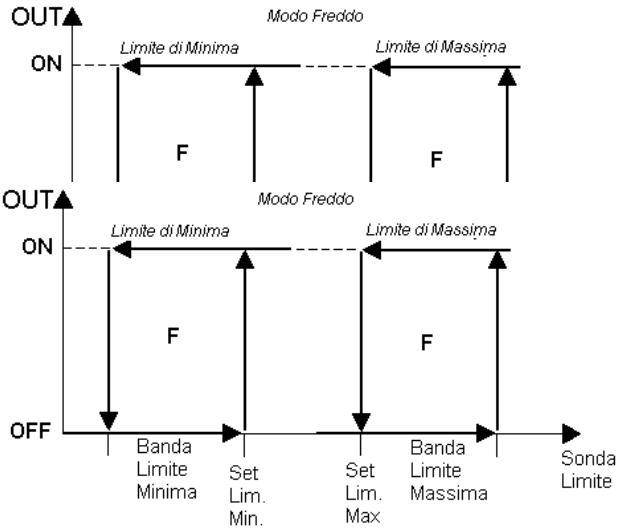




THEREFORE:
In a **HEATING LOOP:**
If the **Minimum limit** function is enabled, it uses the output **maximum value** among the limit Loop and Control Loop. If the **Maximum limit** function is enabled, it uses the output **minimum value** among the limit Loop and Control Loop.

In a **COOLING LOOP:**
If the **Minimum limit** function is enabled, it uses the output **minimum value** among the limit Loop and Control Loop. If the **Maximum limit** function is enabled, it uses the output **maximum value** among the limit Loop and Control Loop.





If the Minimum limit is enabled, it is necessary to define:

- MINIMUM LIMIT SET POINT
- MINIMUM LIMIT PROPORTIONAL BAND

If the Maximum limit is enabled it is necessary to define:

- MAXIMUM LIMIT SET POINT
- MAXIMUM LIMIT PROPORTIONAL BAND

For Operating Modes 3A, 4A and 3D it is necessary to set the Limit Set and Band values both for heating Loop and for cooling Loop. It is not possible to enable the limit function in Operating Mode 4D. The Limit Loop Set-point operates at fixed point and is not modified even under *Reduced* Operating Mode. The Limit Loop is disabled under *Stop* Operating Mode. The Limit function can also be used to create a Control Loop, which performs a control of the SL sensor value independently from sensor SR (see following paragraph).

The **L**imit **S**ensor used is the one connected to **SL** input**,** if not differently specified (“SL sharing” see paragraph related to Link Bus). Connect or share the **L**imit **S**ensor before enabling the minimum and/or maximum Limit. If the Limit is enabled on any Operating Mode and the **L**imit **S**ensor is not connected correctly to **SL** terminal or is not shared correctly with other devices, the Anomaly Led ⓘ switches on.
For all limit parameters settings see page 16.

SECOND LOOP WITH LIMIT SENSOR

If the first loop does not use the Limit Function, it is possible to use the Limit Sensor as Control Sensor for the second Loop. In this case, the second loop can be P type only with fixed Set point.

It is necessary to set the values for the Control Loop in such a way that only the limit action becomes operating. For example, for a heating Loop that controls the SL sensor value, set an Operating Mode 1 (A or D), set the Control Set-point at the minimum value allowed (-50°C) and enable the Minimum limit. The output controls the Set point and the Proportional Band of Minimum limit loop.

For example if the main control Loop on the first analogue output ("PA1") has been set freely, set the loop on the second output ("PA2") as follows:
SETTING PARAMETERS FOR THE SECOND HEATING LOOP
Set the Loop in MODE 1 (heating)
Enable the Minimum limit
Adjust the Control Set at the lowest value, –50°C, (in this way the output stated by the Control Loop will always be zero)
Set the Minimum limit set
Set the Proportional Band of the Minimum limit

SETTING THE PARAMETERS FOR THE SECOND COOLING LOOP
Set the Loop in MODE 2 (Cooling)
Enable the Maximum limit
Adjust the Control Set to the highest value equal to 150 °C (in this way the output stated by the Control Loop will always be zero)
Set the Maximum limit set
Set the Proportional Band of the Maximum limit

OPERATING MODE

The equipment is able to operate according to three different operating modes, which are:

0) Comfort – all loops are ON during control (including the Limit Loop).
1) Reduced – the Control Loops operate on a reduced Set point. The Limit Loops remain ON.
2) Stop – all loops are 0 (including the Limit Loop).

The Operating Mode acts in parallel on all Control Loops also in Mode 4D (sequence controller), in which Comfort and Reduced modes have the same meaning.
The passage from an Operating Mode to another can take place as follows:

- Using the apposite Manual override key Ovr . If it is pressed repeatedly, it is possible to access manually to one of the three modes. This function is enabled on each Control Loop, by setting ABO = On.
  For further details see page 11.

- From *Time schedule:* it changes automatically into one of the three modes. This function is enabled on each Control Loop, by setting ABO = On.

- Through digital input D.i.1 and/or input D.i.2 (except modes 3A and 3D); if enabled (AE1 = On and/or AE2 = On), it is possible to pass from Stop (open contact) to another mode, i.e.:

Changeover from digital inputs with dry contact operates on all Loops whose function is enabled (AE1 or AE2 with value On). Such operation has a priority with respect to other changeovers (from clock or Manual override button).
The Stop mode in Mode 4A produces a 5,5 Vdc output.
The enabled Operating Mode is signalled by a proper Led **Mode** on the front panel, as follows:

Led Mode Status	**Operating Mode enabled**
ON	Comfort
Blinking	Reduced
Off	Stop

Through the Link Bus, it will be possible to share the override mode although a local override on a single equipment has always priority with respect to the shared mode.
The Operating mode is determined by default by the Time schedule, if the clock is present, otherwise the default Operating Mode is Comfort. The manual override through key loses its action, if the equipment is switched off and then on again. For further details, see the three following paragraphs.

MANUAL OVERRIDE KEY FOR THE OPERATING MODE

It is possible to carry out a manual override of the Operating Mode by pushing the proper key Ovr inside the *Operating Mode Programme Menu* accessed by pushing the **Set** key for 5 seconds.
The manual override cancels the mode determined by the clock and it is signalled by the Led **Ovr** on the front panel. The number of clicks on such key, states cyclically the setting, passing from Comfort, to Reduced and Stop modes, then returning to Automatic mode.

CLOCK ENABLE WITH TIME SCHEDULE

If the W500 is RTC-provided or it is connected via Link Bus to a device with clock, it is possible to define the Operating Mode according to a weekly schedule and a daily schedule. The clock enable of each Control Loop is obtained by setting the parameter ABO = On. If the device with clock is connected to other equipments without clock through the Link Bus, the mode can be shared and all the equipments will follow simultaneously the same time schedule.

Weekly schedule:
For each day of the week it is possible to define a fixed mode (0 = Comfort, 1 = Reduced, 2 = Stop) or to assign a daily schedule (expressed by value 3).

Daily schedule:
It is possible to carry out up to 4 time changeovers defining, for each one, hour, minute and mode.
The changeovers, which are not used, must be filled in with the same values of the last valid changeover.

For the setting of both weekly and daily time schedules, see page 21.

OUTSIDE DIGITAL ENABLE

Two digital inputs are available: they can be used independently by the 4 Control Loops. If on a Control Loop the Outside enable (AE1 or AE2 a value On) has been started, it is possible to start and/or stop the Loop from an outside contact. If both the outside enables are ON, the Control Loop stops only if both contacts are open.
For clock models, the contact enables only the loop outside the operating time (if the equipment is "On" from the clock, it cannot be set to off by digital input)
If the Loop is configured to operate in Mode 3A or 3D (Heating / Cooling by S/W Changeover) the digital input 2 is used only for this purpose. The enabling from contact acts a priority with respect to the other changeovers (from clock or manual override with **Ovr** key).

Operating Mode ON	Contact D.i.1 AE1 = On		Contact D.i.2 (*) AE2 = On	
	Open	Closed	Open	Closed
COMFORT	STOP	COMFORT	STOP	COMFORT
RIDOTTO	STOP	REDUCED	STOP	REDUCED
STOP	STOP	COMFORT	STOP	COMFORT

(*) This function is not ON in 3A and 3D modes.

FACTORY DATA LOAD

Through this function it is possible, if required, to reset all the factory settings of parameters.
This function is useful for example when the user has set different values and requires restoring the initial conditions in a short time.

STORING DATA IN PERMANENT MEMORY

Once the parameters for a plant are set, it is possible to store such settings in order to restore them when required.

LOADING DATA FROM PERMANENT MEMORY

This function allows restoring all the configurations and the parameters, which were previously saved by MEMORY DATA STORAGE function.

REMOTE SET

When a control with Fixed-point set is required, the Compensation Sensor is not used.
In this case, it is possible to connect a suitable potentiometer (instead of the **Compensation Sensor** local input) to carry out a remote setting of the Operation Set-point.

PARAMETER SETTING
Enable Compensation and define the four points of the line:
Keep into the account that TEMPERATURE 1 corresponds to the value read at a potentiometer end and TEMPERATURE 2 to the value read at the other end.

- SET 1 corresponding to TEMP 1
- SET 2 corresponding to TEMP 2

The value displayed by the Compensation Sensor is purely indicative and does not correspond to the actual temperature in °C.

OUTSIDE SENSOR FROM SUPERVISION FOR COMPENSATION

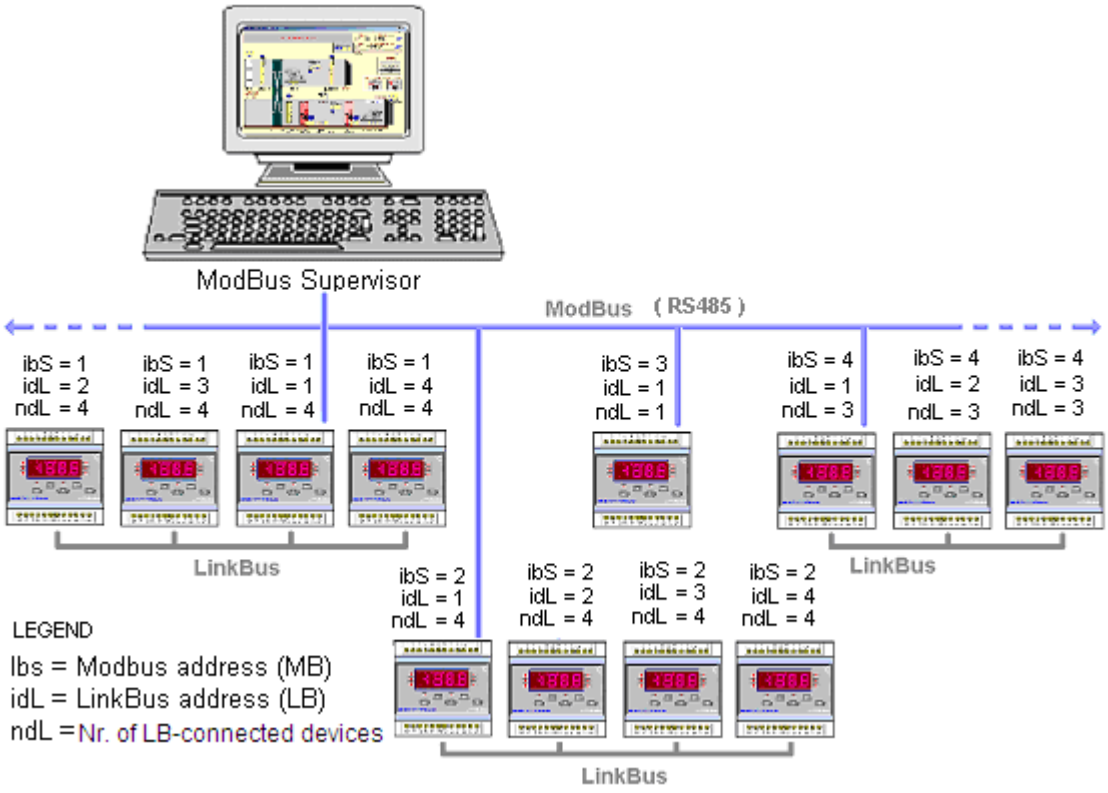
If the function is ON (USE = On), it is possible to carry out compensation through a value sent from the Communication Bus with ModBus protocol (supervision). In practice it is a virtual sensor, which can be used instead of a real sensor connected to **SC** terminal. If, for example, there is only one outside sensor in the whole plant, this function allows using its value on all controllers connected to the supervision system. Similarly it would be possible, from supervision, to set a single Operation Set-point for the different equipments connected.

LINK BUS COMMUNICATION

The Link Bus serial communication port allows to 2, 3 or 4 equipments to interoperate for data exchange. The Link Bus connection allows sharing the three sensors and Operating Mode and supervising the devices, which do not have the RS485 serial communication port.

The equipments connected via Link Bus must have a univocal address (IDL) that can be set by the menus from 1 to 4. The equipment with IDL = 1 (Master) communicates its Operating Mode to the other controllers connected to the Link Bus. If the Master is RTC-provided (RTC is not necessary for the others), the 4 controllers can operate according to the same time schedule. The equipments without the RS485 (W500T) serial communication port can be supervised if connected via Link Bus to at least one equipment with RS485 (W500TMB), setting it as Master.

Each IDL address corresponds to a Link Bus "channel" on which the controller communicates the values of its own temperature sensors connected to the terminals. Each device communicates its values on the Link Bus channel determined by the assigned IDL address number. If it is required a sensor connected to the terminals of another controller, it is necessary to operate on parameters menu of Sensor Selection (SEL) and to select the channel for reading. For example, a controller with IDL address = 2, which uses the Compensation Sensor connected to **SC** terminals of the equipment having IDL address = 3, the value SSC in the sensor selection parameter menu (SEL) must be = 3. If the sensor to be used is connected to the controller terminals, the setting will be SSC = 2. For each one of three sensors it is necessary to specify its location. If the sensor is local, it is necessary to state the proper IDL address.



In order to communicate the values through the Link Bus port, it is also necessary to set the number of devices interconnected by the parameter NDL (4 max.). The equipments connected to the Link Bus, which must not transmit data, can be set with NDL = 1. Such configuration is allowed (to speed data exchange on the Link Bus), but it is not recommended in case of data monitoring via ModBus. The equipments connected to the Link Bus which do not communicate data, can receive data from other equipments. It is essential that:

- the other equipments have the same NDL value as the number of the controllers, communicating the values
- the equipments, which do not communicate data, have a higher IDL address.

The equipments, which are RTC-provided, always use the their Operating Mode changeover ignoring the Link Bus signal.

The max advisable distance between the two equipments at the Link Bus ends is 10 m. This distance should allow any connection inside the electrical board. In case of power devices (Contactors, Inverters, UPS, reactors, etc.) it **is strongly recommended to use shielded cables** with the screen connected to earth at one point only and to keep at a suitable distance (30 cm. at least) the power cables and the signal wires, otherwise use metal pipes.

It is advisable to use a 24AWG or 26AWG twisted-pair cable and do not carry out star connections.

For setting the Link Bus address and to select one of the sensors shared, see page 16.

MODBUS COMMUNICATION

Through the ModBus protocol it is possible to supervise up to 255 groups of 4 equipments, for a total of 1020 devices. The ModBus connection is carried out on the equipment defined with IDL = 1 (Master) through the RS485 serial port. The values managed by supervision and those managed by the controller menu are the same.

For the address values of ModBus data, refer to the proper DataBase documents supplied on request.

The wiring path between the two most distant devices connected to RS485 serial must not exceed 1000 m.: we recommend to use a 24AWG or 26AWG twisted-pair cable and not to carry out star connections.

The first and the last device must be terminated by a 120-Ohm ¼-Watt resistance.
If devices from different manufacturers are present on the same communication Bus, it is necessary to respect the limits imposed and to be careful not to use the same ModBus addresses of other devices. We recommend using a shielded cable for RS485 Bus if on the plant or inside the switchboard are present power devices, always keeping the suitable distances and precautions regarding signal wiring and power cables.

For ModBus address set up and outside compensation from supervision, see page 21.

ERROR SIGNALLING

The controller is able to signal two anomaly conditions, one depending from communication and the other from Sensors.
If a Communication ERROR is present, the Anomaly Led ⓘ blinks. It is possible to have a communication fault when, for example, two equipments connected via Link Bus use the same IDL address or in case of high noise on communication, which provokes faulty data transmission. Inside switchboards, in presence of power devices (contactors, Inverters, UPS, reactors, etc.), **we recommend to use shielded cables** (both for sensors and Bus) to reduce anomaly probability.
If a sensor anomaly occurs, the Anomaly Led ⓘ lights up. If both anomaly conditions occur, the Led blinks. Once the Communication anomaly is cancelled, the Led remains on indicating the Sensor ERROR.
For a correct operation the anomaly Led must be switched off.
The conditions, which most frequently produce anomalies, are:

- Sensor is no more present with enabled function
- Sensor outside the controller (shared with Link Bus) is not present
- More devices have the same IDL address

FRONT PANEL AND DATA ACCESS MENU

Using Front Panel, it is possible to access the Parameters managed by the device. The data access Menu is subdivided into three different levels:

Level 0 – Main data display
Level 1 – Access to parameter configuration menu
Level 2 – Access to the Operating modes programming menu

The **Level 0** is the one displayed by default. If no keys are pushed for some seconds this level is automatically re-entered from the higher levels.
At this Menu level it is possible to visualize on the FND display the temperature values of the connected sensors (also via Link Bus) and the analogue outputs Ao1 and Ao2 values expressed as a percentage. Data display is achieved by pushing the buttons **Up** or **Down**; while Led signalling the displayed analogue input or output lights up. If an input is not present, it is not displayed. The digital input led **D.i.1** and **D.i.2** are on with closed contact, the **Rel1** and **Rel2** relay output led are on if they are energized. Such led are always visible at any menu level. The **Mode, Ovr** and anomaly ⓘ LEDs have already been described in the respective chapters.

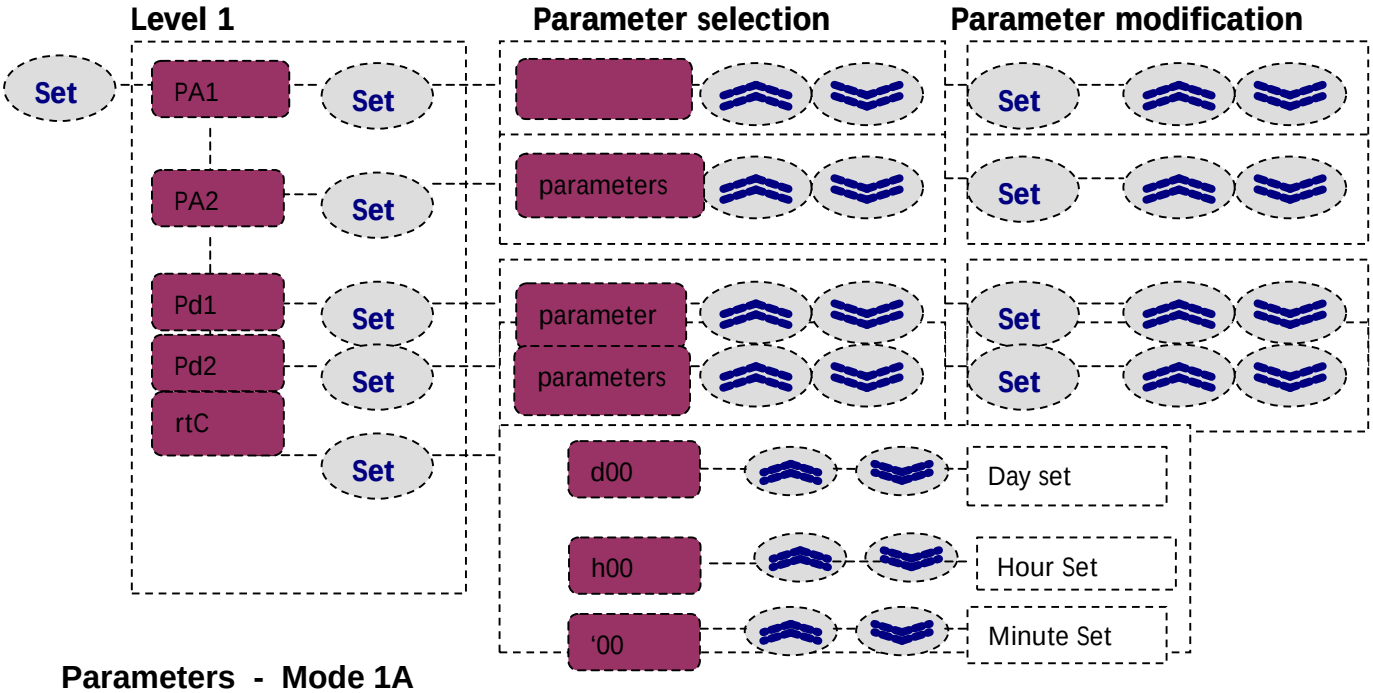
To access **Level 1,** push the Set key. At this level it is possible to change the control Parameters of the two analogue outputs [**PA1**] and [**PA2**], of the two Relay Digital outputs [**Pd1**] and [**Pd2**] and, for W500TMB controllers only, also the clock [**rtc**]. It is always necessary to set the clock at the first start-up or if the equipment has been powered off for over 30 hours. In order to set date and time, scroll the menu at the level 1 until the corresponding label [**rtc**] is reached. The label [**d00**] (days, d00 = Monday) appears by pushing the **Set** key. Push the buttons **Up** or **Down** to set. If the key are not pushed for some seconds or by pressing **Set**, the label [**h00**] (hours) and [**'00**] (minutes) appears: push the buttons **Up** and **Down** to set respectively hour and minutes. To confirm and save, push **Set**. If the keypad is not pushed or by pressing the **Esc** key once, the start value appears.
[PA1] label corresponds to the **P**arameters of **A**nalogue output **1** at **Ao1** terminal
[PA2] label corresponds to the **P**arameters of **A**nalogue output **2** at **Ao2** terminal
[Pd1] label corresponds to the **P**arameters of **D**igital output **1** of **Rel1** relay
[Pd2] label corresponds to the **P**arameters of **D**igital output **2** of **Rel2** relay

To modify a parameter, it is necessary to push **Set** after selecting the corresponding Label; the parameter value blinks and can be changed by pushing the keys **Up** to increase or **Down** to decrease. Push **Set** or **Esc** to exit. For the complete control parameter navigation see the *Parameter Configuration Menu* scheme on page 17.

By pushing the **Set** key for at least 5 seconds, **Level 2** appears. At this menu level, it is possible to set:
- the Operating-Set decrease to Reduced mode
- the operating modes of the two analogue outputs [**PA1**] and [**PA2**] and of the two relay digital outputs [**Pd1**] and [**Pd2**]
- the address parameters for communication, for sensor selection, for data load, save, restore and, for W500TMB devices only, also the time schedules for the automatic changeover of the weekly and daily Operating Mode.

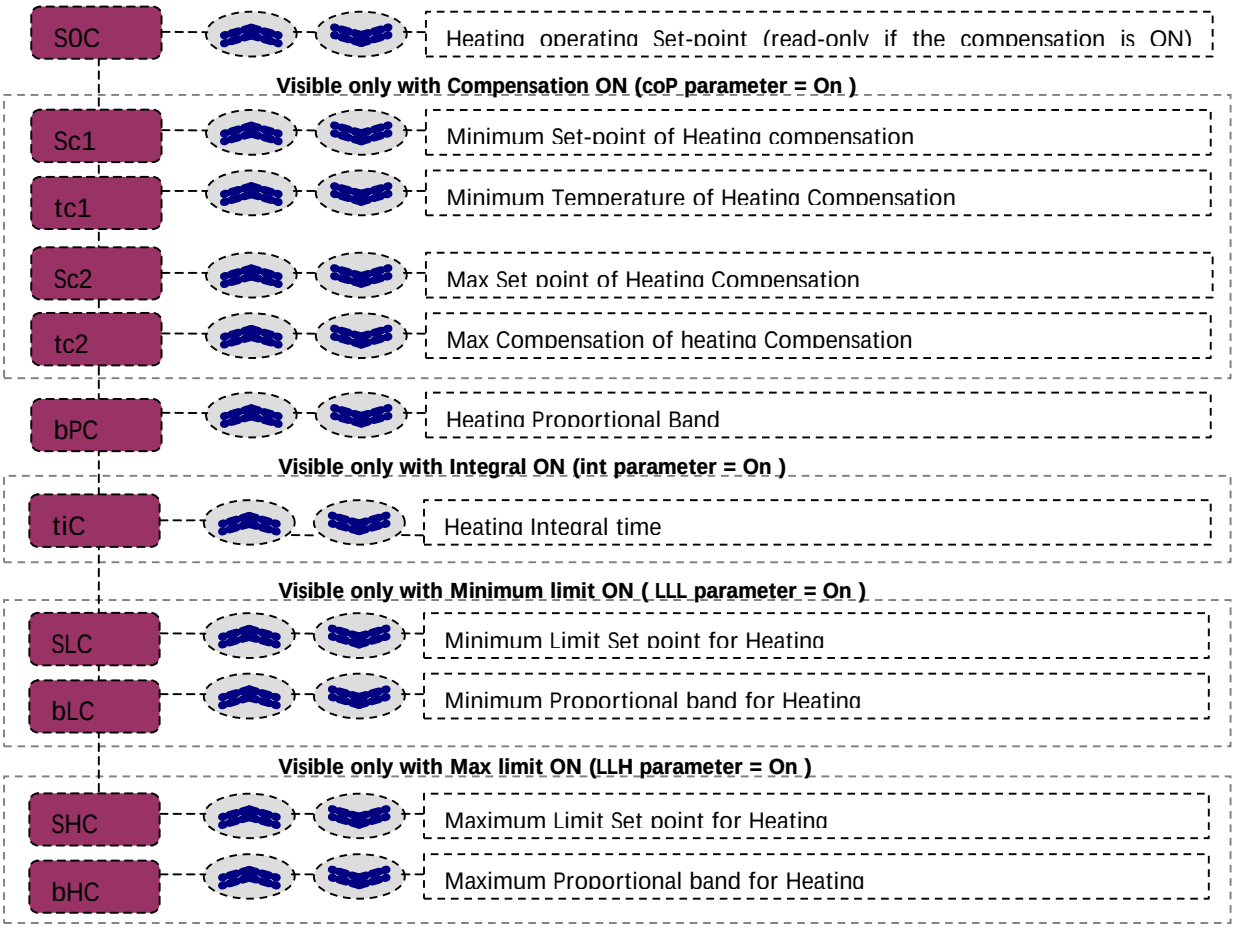
For data navigation see *Programme menu for operating mode and time schedules* on page 21 Note: the time schedules are present only on W500TMB.

PARAMETER CONFIGURATION MENU



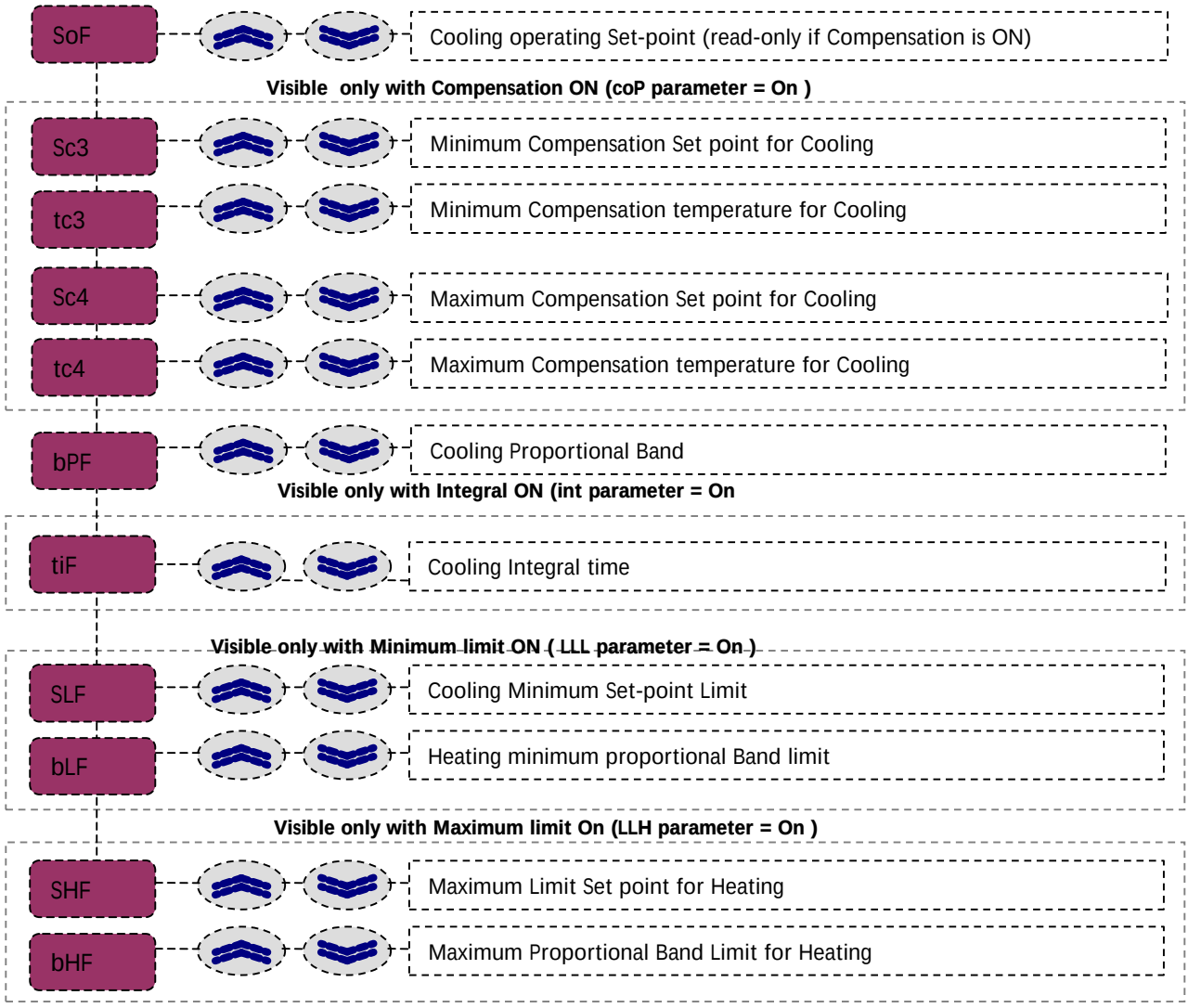
Parameters - Mode 1A

Push the **Set** Key to change of the relevant parameter. The parameter value blinks showing the edit status: push the **Up** and **Down** keys to change values. Once the desired values are modified, push the **Set** or **Esc** keys to exit.


SOC
Heating operating Set-point (read-only if the compensation is ON)
Visible only with Compensation ON (coP parameter = On)
Sc1
Minimum Set-point of Heating compensation
tc1
Minimum Temperature of Heating Compensation
Sc2
Max Set point of Heating Compensation
tc2
Max Compensation of heating Compensation
bPC
Heating Proportional Band
Visible only with Integral ON (int parameter = On)
tiC
Heating Integral time
Visible only with Minimum limit ON (LLL parameter = On)
SLC
Minimum Limit Set point for Heating
bLC
Minimum Proportional band for Heating
Visible only with Max limit ON (LLH parameter = On)
SHC
Maximum Limit Set point for Heating
bHC
Maximum Proportional band for Heating

Parameters - Mode 2A

Push **Set** key to select the parameter to be modified. The parameter value blinks showing the edit status: push the **Up** and **Down** keys to change values. Once the desired values are modified, push the **Set** or **Esc** keys to exit.


SoF
Cooling operating Set-point (read-only if Compensation is ON)
Visible only with Compensation ON (coP parameter = On)
Sc3
Minimum Compensation Set point for Cooling
tc3
Minimum Compensation temperature for Cooling
Sc4
Maximum Compensation Set point for Cooling
tc4
Maximum Compensation temperature for Cooling
bPF
Cooling Proportional Band
Visible only with Integral ON (int parameter = On
tiF
Cooling Integral time
Visible only with Minimum limit ON (LLL parameter = On)
SLF
Cooling Minimum Set-point Limit
bLF
Heating minimum proportional Band limit
Visible only with Maximum limit On (LLH parameter = On)
SHF
Maximum Limit Set point for Heating
bHF
Maximum Proportional Band Limit for Heating

Parameters - Mode 3A / Mode 4A

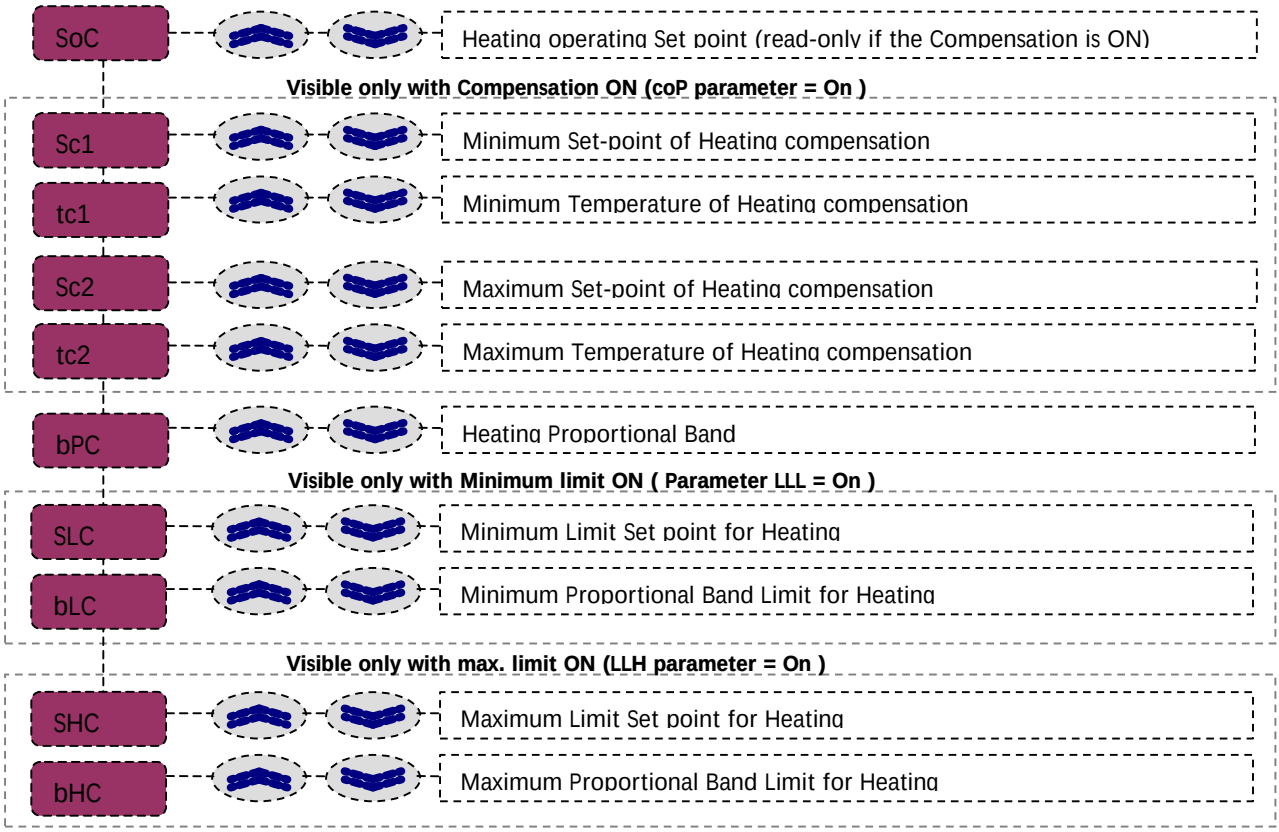
The parameter menu of the Analogue Operating Modes 3A/4A is the sum of 1A/2A Modes parameter menus. This Menu contains all parameters, since this modes are intended manage both heating and cooling control loops.

Push **Set** key to select the parameter to be modified. The parameter value blinks showing the edit status: push the **Up** and **Down** keys to change values. Once the desired values are modified, push the **Set** or **Esc** keys to exit.

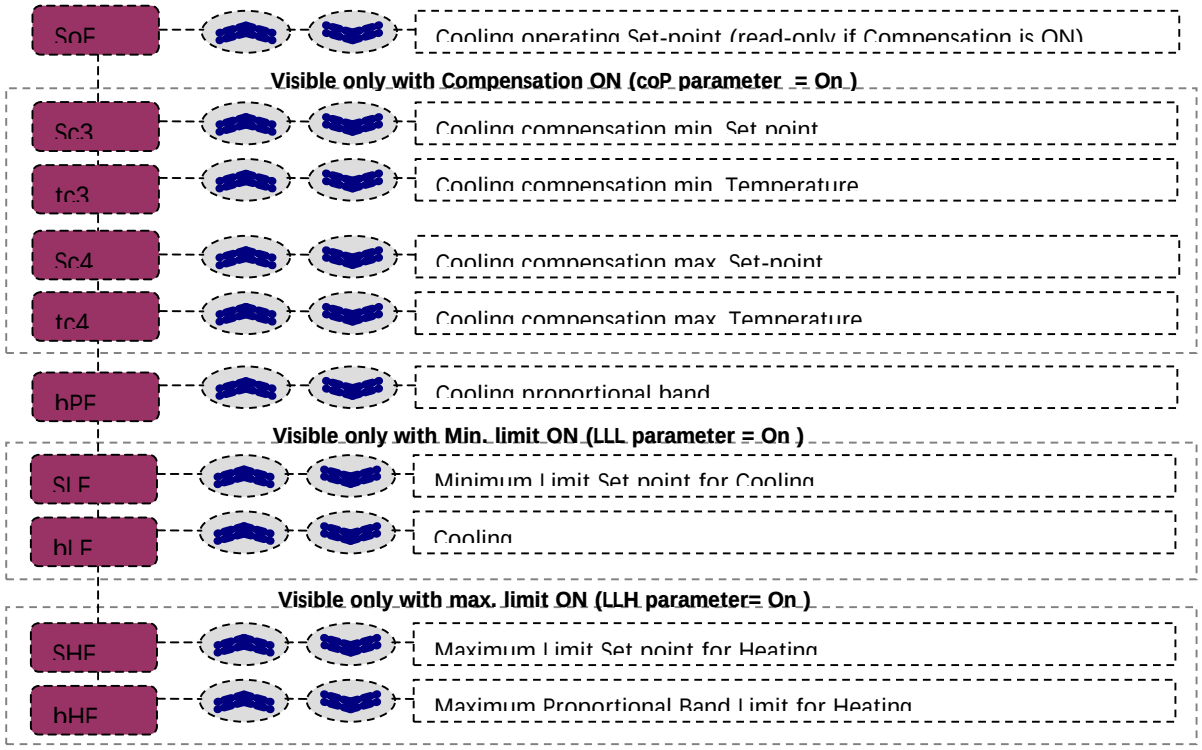
The Compensation/Integral/Limit parameters are visible if the relevant functions in the Operating Mode Programme menu (2° Level) are enabled. Push **Set** key for 5 seconds to enter the menu.

Parameters - Mode 1D

Push **Set** key to select the parameter to be modified. The parameter value blinks showing the edit status which is carried out by pushing the **Up** key to increase the value and **Down** to decrease it. Once the desired values are modified, push the **Set** or **Esc** keys to exit.


SoC
Heating operating Set point (read-only if the Compensation is ON)
Visible only with Compensation ON (coP parameter = On)
Sc1
Minimum Set-point of Heating compensation
tc1
Minimum Temperature of Heating compensation
Sc2
Maximum Set-point of Heating compensation
tc2
Maximum Temperature of Heating compensation
bPC
Heating Proportional Band
Visible only with Minimum limit ON (Parameter LLL = On)
SLC
Minimum Limit Set point for Heating
bLC
Minimum Proportional Band Limit for Heating
Visible only with max. limit ON (LLH parameter = On)
SHC
Maximum Limit Set point for Heating
bHC
Maximum Proportional Band Limit for Heating

Parameters - Mode 2D



Parameters - Mode 3D

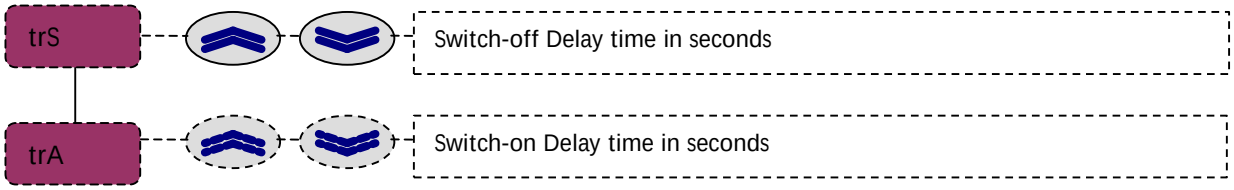
The Parameter menu of On/OFF Hysteresis Digital operating Mode 3D is the sum of 1D/2D Modes parameter menus. This Menu contains all parameters, since this mode is intended to manage both heating and cooling control loops.

Push **Set** key to select the parameter to be modified. The parameter value blinks showing the edit status: push the **Up** and **Down** keys to change values. Once the desired values are modified, push the **Set** or **Esc** keys to exit.

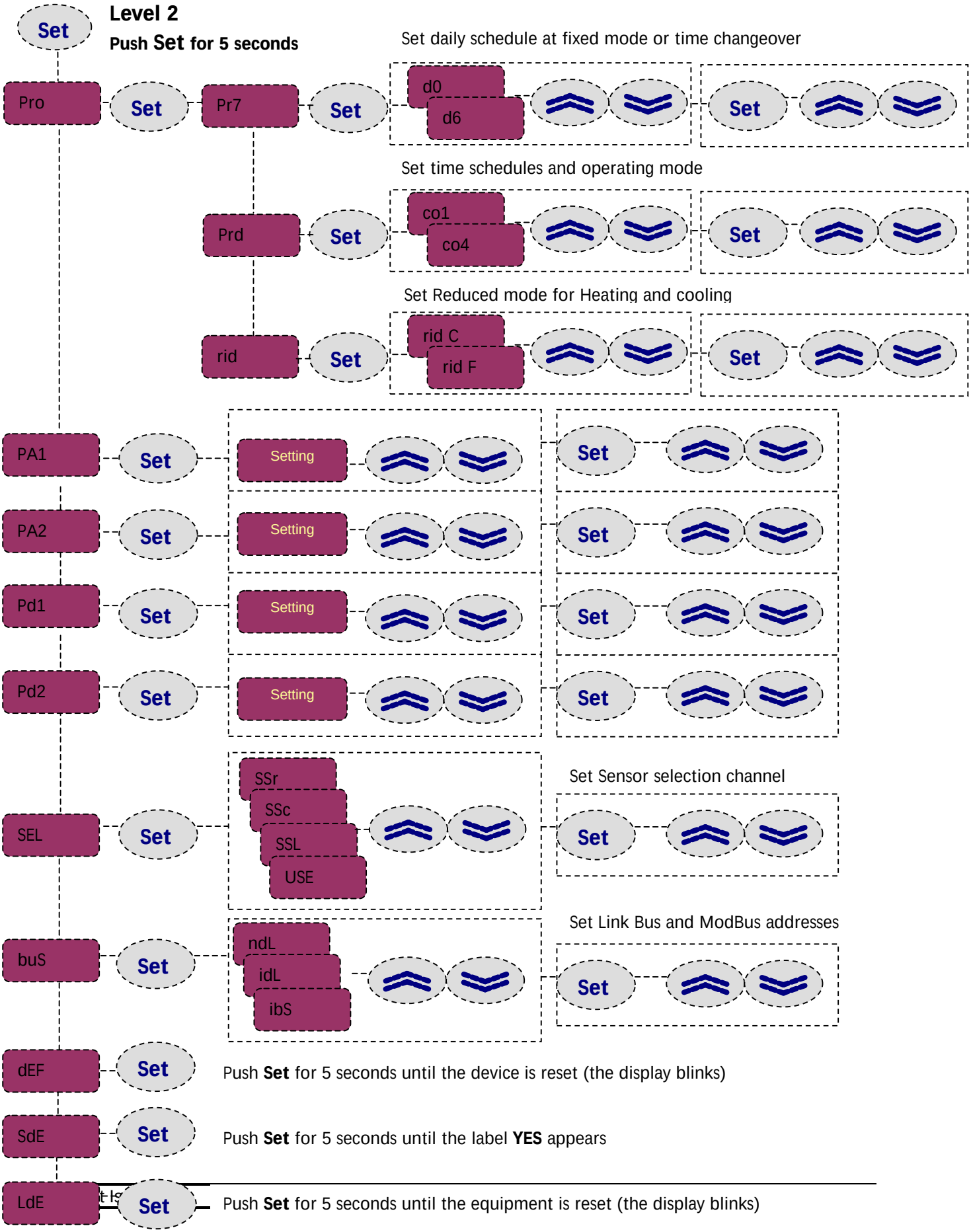
The Compensation and Limit parameters are visible if the relevant functions in the Operating Mode Programme menu (2° Level) are enabled. Push **Set** key for 5 seconds to enter such menu

Parameters - Mode 4D

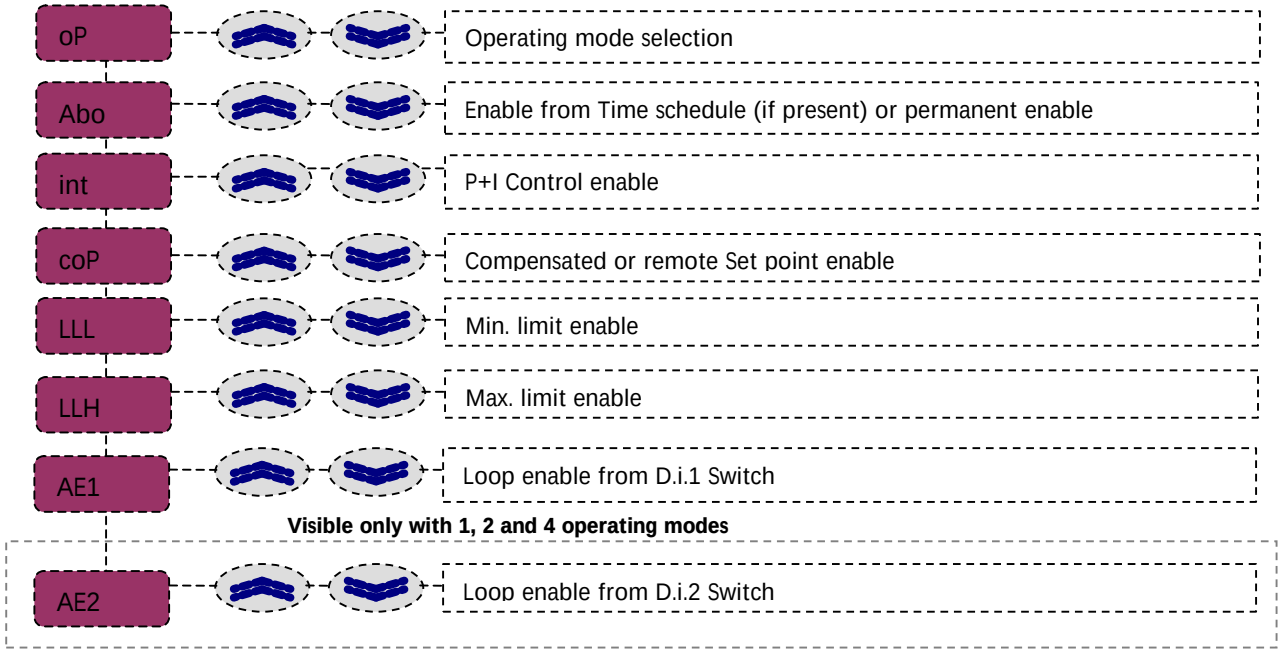
Push **Set** key to select the parameter to be modified. The parameter value blinks showing the edit status: push the **Up** and **Down** keys to change values. Once the desired values are modified, push the **Set** or **Esc** keys to exit.



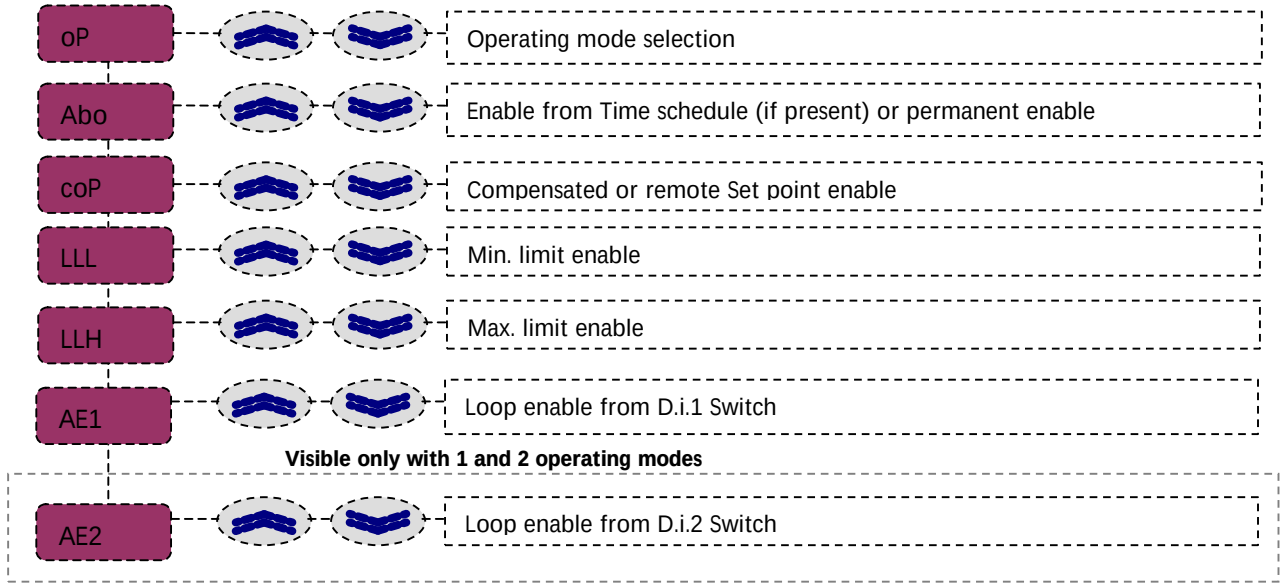
PROGRAMME MENU FOR OPERATING MODES AND TIME SCHEDULES



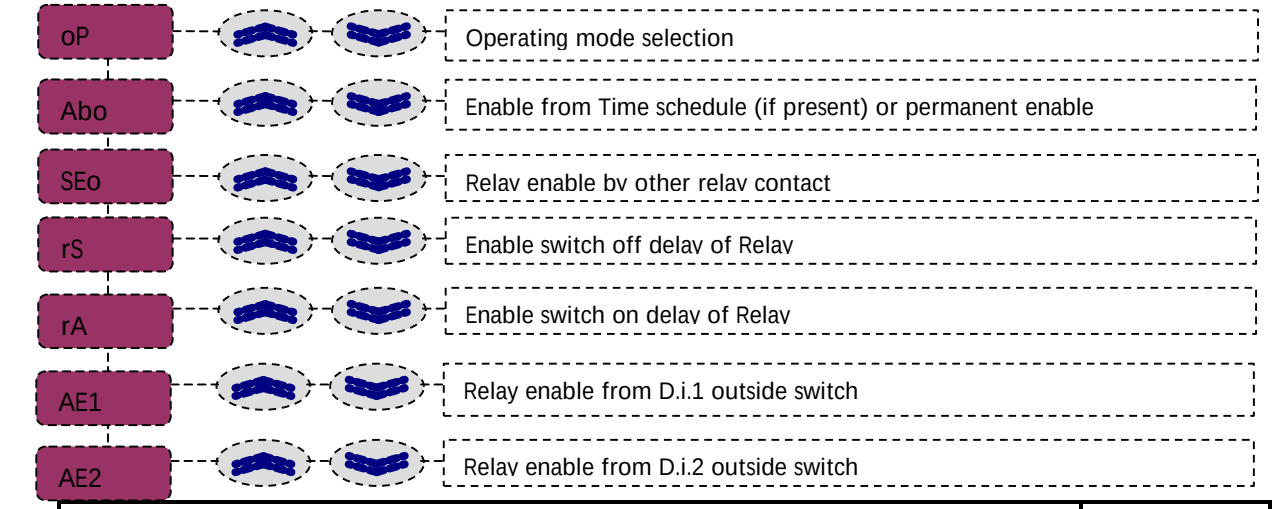
Settings - 0-10Volt Analogue Outputs (PA1 and PA2)



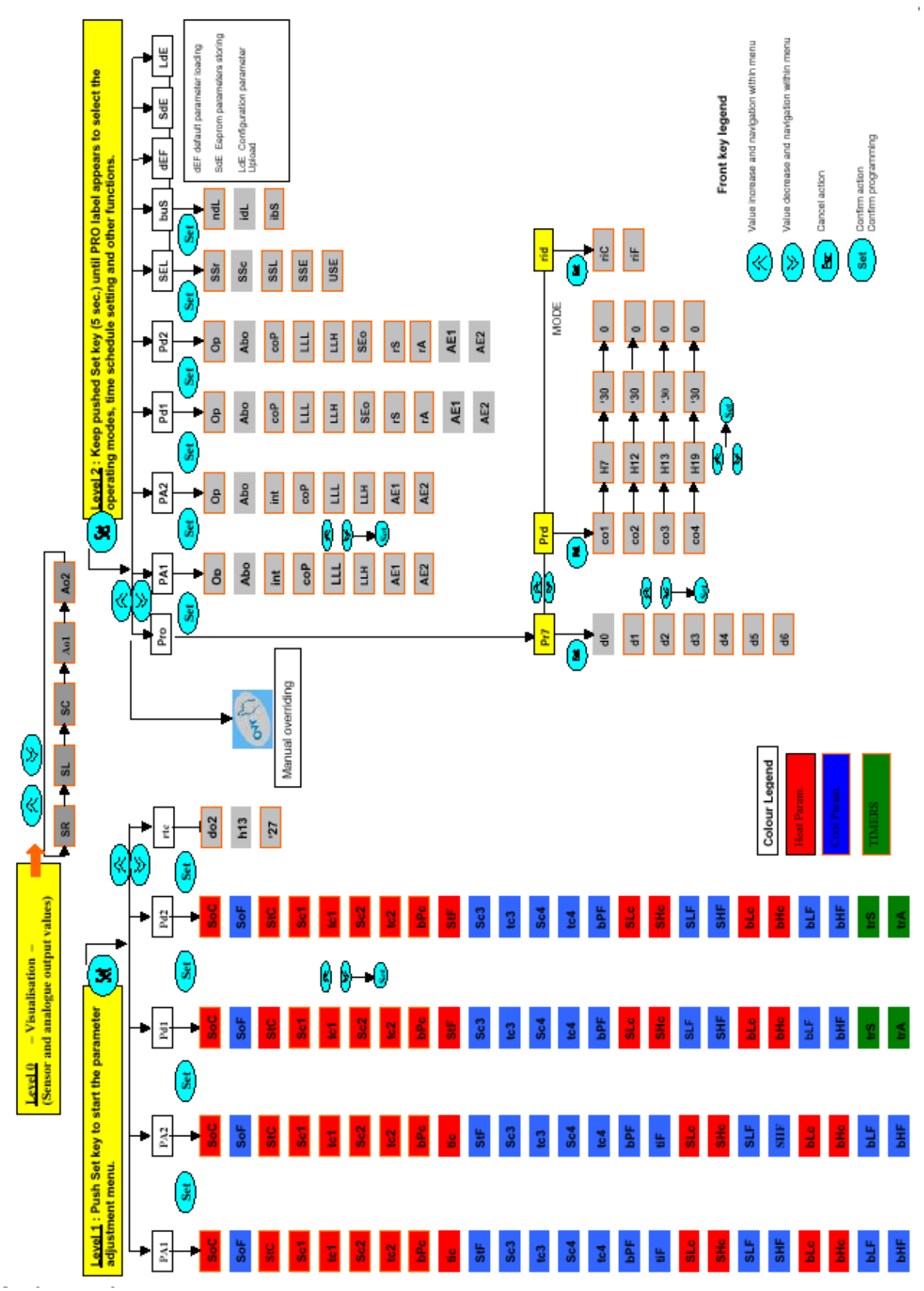
Settings - Relay Digital Outputs (Pd1 and Pd2) – Operating Modes 1, 2 and 3



Setting - Relay digital Outputs (Pd1 and Pd2) – Operating Mode 4



MENU DIAGRAM


Level 0 : Visualisation
(Sensor and analogue output values)
Level 1 : Push Set key to start the parameter adjustment menu.
Level 2 : Keep pushed Set key (5 sec.) until PRO label appears to select the operating modes, time schedule setting and other functions.
Manual overriding
MODE
Front key legend
Value increase and navigation within menu
Value decrease and navigation within menu
Cancel action
Confirm action
Confirm programming
Colour Legend
Heat Param.
Cool Param.
TIMERS

CONTROL PARAMETER TABLES (LEVEL 1)

Parameter table: Level 1 (Loop adjustment Parameters)

Analogue Controller PA1 & PA2	Default	Range	Description	Availability
SoC	--		Heat operating Set	Always (Visualisation only, cannot be set)
SoF	--		Cool operating Set	Always (Visualisation only, cannot be set)
StC	21.0	-50 to 150	Heat Loop Set	With SR, without Compens., 1, 3 and 4 operating mode
Sc1	20.0	-50 to 150	Heating compensation min. Set	With SR and SC, Comp. enabled, 1, 3 and 4 operating mode
tc1	5.0	-50 to 150	Heating compensation min. temperature	With SR and SC, Comp. enabled, 1, 3 and 4 operating mode
Sc2	35.0	-50 to 150	Heating compensation max. Set	With SR and SC, Comp. enabled, 1, 3 and 4 operating mode
tc2	10.0	-50 to 150	Heating compensation max. temperature	With SR and SC, Comp. enabled, 1, 3 and 4 operating mode
tiC	480	30 to 1200	Heating integral time (sec)	With integral action enabled
bPc	4.0	0 to 25	Heating Loop Proportional Band	With SR, 1, 3 and 4 operating mode
SLc	18.0	-50 to 150	Heating min. limit Loop Set	With LLL enabled, 1, 3 and 4 operating mode
SHc	24.0	-50 to 150	Heating max. limit Loop Set	With LLH enabled, 1, 3 and 4 operating mode
SLF	18.0	-50 to 150	Cooling min. limit Loop Set	With LLL enabled, 2, 3 and 4 operating mode
SHF	24.0	-50 to 150	Cooling max. limit Loop Set	With LLH enabled, 2, 3 and 4 operating mode
bLc	4.0	0 to 25	Heating min. limit. Proportional Band	With LLL enabled, 1, 3 and 4 operating mode
bHc	4.0	0 to 25	Heating max. limit Proportional Band	With LLH enabled, 1, 3 and 4 operating mode
bLF	4.0	0 to 25	Cooling min. limit Proportional Band	With LLL enabled, 2, 3 and 4 operating mode
bHF	4.0	0 to 25	Cooling max. limit Proportional Band	With LLH enabled, 2, 3 and 4 operating mode
StF	23.0	-50 to 150	Cooling Loop Set	With SR, without Compens., 2, 3 and 4 operating mode
Sc3	10.0	-50 to 150	Cooling compensation min. Set	With SR and SC,Comp. enabled, 2, 3 and 4 operating mode
tc3	10.0	-50 to 150	Cooling compensation min. Temperature	With SR and SC,Comp. enabled, 2, 3 and 4 operating mode
Sc4	30.0	-50 to 150	Cooling compensation max. Set	With SR and SC, Comp.enabled, 2, 3 and 4 operating mode
tc4	15.0	-50 a 150	Cooling compensation max. Temperature	With SR and SC, Comp. enabled, 2, 3 and 4 operating mode
tiF	480	30 a 1200	Cooling integral time (sec)	With integral action enabled
bPF	4.0	0 to 25	Cooling Loop Proportional Band	With SR, 2, 3 and 4 operating mode
Reg. On/Off Pd1 & Pd2	**Default**	**Range**	**Description**	**Availability**
SoC	--		Heating operating Set	Always (Visualisation only, cannot be set)
SoF	--		Cooling operating Set	Always (Visualisation only, cannot be set)
StC	21.0	-50 to 150	Heating ON/OFF Set	With SR, without Compens., 1 and 3 operating mode
Sc1	20.0	-50 to 150	Heating compensation min. Set	With SR and SC, Comp. enabled, 1 and 3 operating mode
tc1	5.0	-50 to 150	Heating compensation min. Temperature	With SR and SC, Comp. enabled, 1 and 3 operating mode
Sc2	35.0	-50 to 150	Heating compensation max. Set	With SR and SC, Comp. enabled, 1 and 3 operating mode
tc2	10.0	-50 to 150	Heating compensation max. Temperature	With SR and SC, Comp. enabled, 1 and 3 operating mode
bPc	4.0	0 to 25	Heating ON/OFF Hysteresis	With SR, 1 and 3 operating mode
SLc	18.0	-50 to 150	Heating min. ON/OFF limit Set	With LLL enabled, 1 and 3 operating mode
SHc	24.0	-50 to 150	Heating max. ON/OFF limit Set	With LLH enabled, 1 and 3 operating mode
SLF	18.0	-50 to 150	Cooling min. ON/OFF limit Set	With LLL enabled, 2 and 3 operating mode
SHF	24.0	-50 to 150	Cooling max. ON/OFF limit Set	With LLH enabled, 2 and 3 operating mode
bLc	4.0	0 to 25	Heating min. ON/OFF limit Hysteresis	With LLL enabled, 1 and 3 operating mode
bHc	4.0	0 to 25	Heating max. ON/OFF limit Hysteresis	With LLH enabled, 1 and 3 operating mode
bLF	4.0	0 to 25	Cooling min. ON/OFF limit Hysteresis	With LLL enabled, 1 and 3 operating mode
bHF	4.0	0 to 25	Cooling max. ON/OFF limit Hysteresis	With LLH enabled, 1 and 3 operating mode
StF	24.0	-50 to 150	Cooling ON/OFF Set	With SR, without Compens., 2 and 3 operating mode
Sc3	8.0	-50 to 150	Cooling compensation min. Set	With SR and SC, Comp. enabled, 2 and 3 operating mode
tc3	0.0	-50 to 150	Cooling compensation min. temperature	With SR and SC, Comp. enabled, 2 and 3 operating mode
Sc4	15.0	-50 to 150	Cooling compensation max. Set	With SR and SC, Comp. enabled, 2 and 3 operating mode
tc4	40.0	-50 to 150	Cooling compensation max. temperature	With SR and SC, Comp. enabled, 2 and 3 operating mode
bPF	4.0	0 to 25	Cooling ON/OFF Hysteresis	With SR, 2 and 3 operating mode
trS	0	0 to 1999	Switch off delay time (sec)	Operating mode 4
trA	0	0 to 1999	Switch on delay time (sec)	Operating mode 4

TABLES OF OPERATING MODES AND TIME SCHEDULES (LEVEL 2)

Parameter table: Level 2 (Time schedules, Operating modes, Special functions)

Time schedules (Pro)

Weekly schedule (Pr7)	Default	Range	Description	Availability
d0 (MON)	3	0 to 3	Fixed mode or daily schedule (NM,RF,FA,PG)	If clock is present (W500TMB model)
d1 (TUE)	3	0 to 3	Fixed mode or daily schedule(NM,RF,FA,PG)	If clock is present (W500TMB model)
d2 (WED)	3	0 to 3	Fixed mode or daily schedule (NM,RF,FA,PG)	If clock is present (W500TMB model)
d3 (THU)	3	0 to 3	Fixed mode or daily schedule (NM,RF,FA,PG)	If clock is present (W500TMB model)
d4 (FRI)	3	0 to 3	Fixed mode or daily schedule (NM,RF,FA,PG)	If clock is present (W500TMB model)
d5 (SAT)	1	0 to 3	Fixed mode or daily schedule (NM,RF,FA,PG)	If clock is present (W500TMB model)
d6 (SUN)	2	0 to 3	Fixed mode or daily schedule (NM,RF,FA,PG)	If clock is present (W500TMB model)
Daily schedule (Prd)	**Default**	**Range**	**Description**	**Availability**
co 1: h	7	0 to 23	Change-over time 1	If clock is present (W500TMB model)
: '	30	0 to 59	Change-over minutes 1	If clock is present (W500TMB model)
: r	0	0 to 2	Change-over mode 1 (NM, RF, FA)	If clock is present (W500TMB model)
co 2: h	12	0 to 23	Change-over time 2 (0-23)	If clock is present (W500TMB model)
: '	30	0 to 59	Change-over minutes 2 (0-59)	If clock is present (W500TMB model)
: r	1	0 to 2	Change-over mode 2 (NM, RF, FA)	If clock is present (W500TMB model)
co 3: h	13	0 to 23	Change-over time 3 (0-23)	If clock is present (W500TMB model)
: '	30	0 to 59	Change-over minutes 3 (0-59)	If clock is present (W500TMB model)
: r	0	0 to 2	Change-over mode 3 (NM, RF, FA)	If clock is present (W500TMB model)
co 4: h	19	0 to 23	Change-over time 4 (0-23)	If clock is present (W500TMB model)
: '	0	0 to 59	Change-over minutes 4 (0-59)	If clock is present (W500TMB model)
: r	2	0 to 2	Change-over mode 4 (NM, RF, FA)	If clock is present (W500TMB model)
Reduced Set (rid)	**Default**	**Range**	**Description**	**Availability**
RiC	3	0 to 20	Heating Set decrease	Always
RiF	5	0 to 20	Cooling Set decrease	Always

Operating modes

Analogue contr. PA1 & PA2	Default	Range	Description	Availability
Op	1	1 to 4	Operating mode (1, 2, 3, 4)	Always **Note: for details about the Operating modes see also the data sheet**
Abo	OFF		Automatic/Manual enable (Clock)	Always
Int	OFF		Integral action enable	Always
coP	OFF		Compensated set enable	With SC sensor
LLL	OFF		Min. limit loop (Low) enable	With SL sensor
LLH	OFF		Max. limit loop (High) enable	With SL sensor
AE1	OFF		Loop stop on DI1 (External enable 1)	Always
AE2	OFF		Loop stop on DI2 (External enable 2)	1, 2 and 4 operating mode. 3 Mode: S/W (off) Changeover
On/Off contr. Pd1 & Pd2	**Default**	**Range**	**Description**	**Availability**
Op	1	1 to 4	Operating mode (1, 2, 3, 4)	Always
Abo	OFF		Automatic/Manual enable (Clock)	Always
coP	OFF		Compensated Set enable	With SC, 1, 2 and 3 operating mode
LLL	OFF		Min. (Low) ON/OFF limit enable	With SL, 1, 2 and 3 operating mode
LLH	OFF		Max. (High) ON/OFF limit enable	With SL, 1, 2 and 3 operating mode
AE1	OFF		Loop stop on DI1 (External enable 1)	Always
AE2	OFF		Loop stop on DI1 (External enable 2)	1, 2 and 4 operating mode. In Mode3: S(on)/W (off) Changeover
SEo	OFF		Other ON/OFF control enable	Operating mode 4
RS	OFF		Switch off delay enable	Operating mode 4
RA	OFF		Switch on delay enable	Operating mode 4

Special Functions

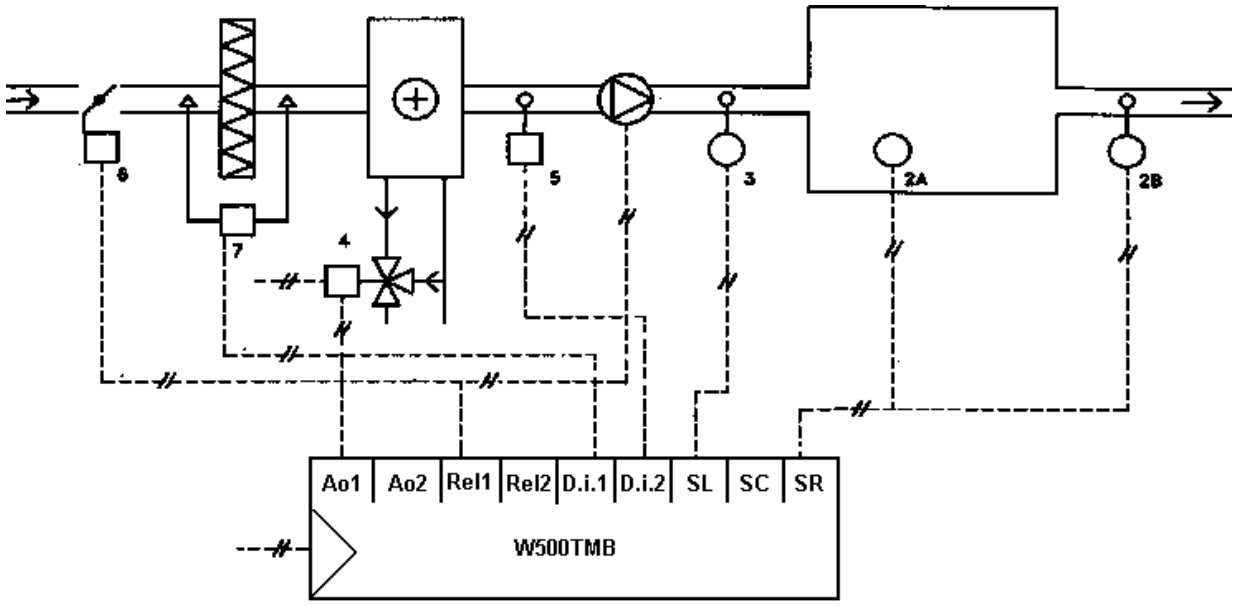
Sensor selection (SEL)	Default	Description	Availability
SSr	1	Control sensor selection	Always
SSc	1	Compensation sensor selection	Always
SSL	1	Limit sensor selection	Always
SSE	1	Selection for external sensor to device	Always
USE	OFF	Compensation sensor enable by ModBus	Always

Communication (buS)	Default	Range	Description	Availability
ndL	1	1 to 4	Number of devices on LinkBus (1 - 4)	Always
idL	1	1 to 4	LinkBus position (1 - ndL)	Always
ibS	1	1 to 255	ModBus Supervisor bus address	Always

SYSTEM APPLICATIONS

EXAMPLE 1:

OUTSIDE AIR PLANT WITH TIME CONTROL OF ROOM TEMPERATURE IN WINTER



OPERATION

The controller carries out time control, with P+I action, on room temperature (sensor 2A) or on air exhaust (sensor 2B) by driving the valve (4) on the heating coil. In case the supply temperature (3) goes below the set limit value, the controller intervenes with P action, changing the valve position to avoid that excessively cold air is introduced into the environment. It is possible to supervise by ModBus also visualizing the status of the differential pressure switch on the filter.

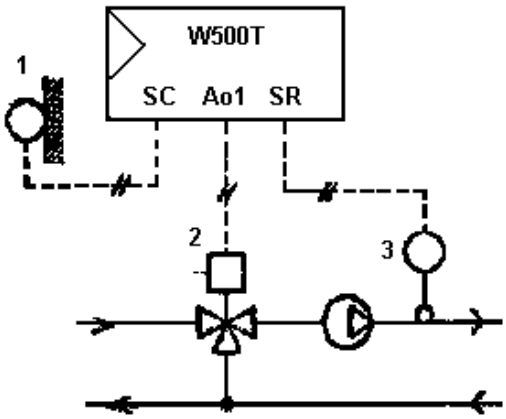
Frost protection: in case of heated fluid lack or of faulty control, if the anti-frost thermostat (5) detects a temperature lower than the set value, the controller stops the fan and closes the outside air damper.

Obstructed filter: the pressure switch (7) signals the presence of obstructed filter if the differential pressure before and after the filter, increases over the set value.

Possible variants:

- fan control on exhaust on digital output **Rel2** with switch-on delay with respect to the supply fan
- remote set point of the heating coil on **SC** input, or compensated outside set point.

EXAMPLE 2:
HOT WATER PLANT FOR FAN COILS

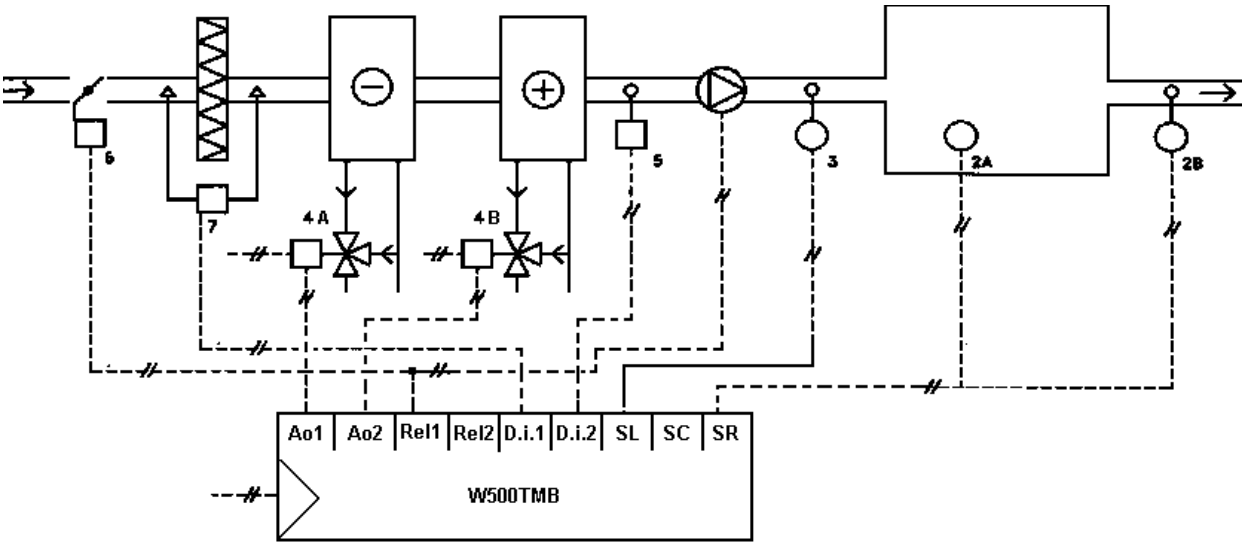


OPERATION

The controller carries out control, by P+I action, of the supply temperature detected by the sensor (3), according to the function value of outside temperature, sensor (1), by driving the proportional motorized valve (2) on the tapping circuit of the power station collector.

Possible variants: control with minimum limit on the return fluid temperature sensor. Time control through W500TMB controller. ModBus supervision through W500TMB controller or proper additional module (BusAdapter).

EXAMPLE 3:
OUTSIDE AIR PLANT WITH TIME TEMPERATURE CONTROL OF HEATING/COOLING ENVIRONMENT



OPERATION

The P+I controller action performs time control of the room temperature (sensor 2A) or air exhaust (sensor 2B) by driving in sequence the valves on the heating (4B) and cooling (4A) coils. The sensor on supply (3), minimum limit, avoids that the air with a temperature below the set value is introduced into the environment. It is possible to supervise by ModBus also visualizing the status of the differential pressure switch on the filter.

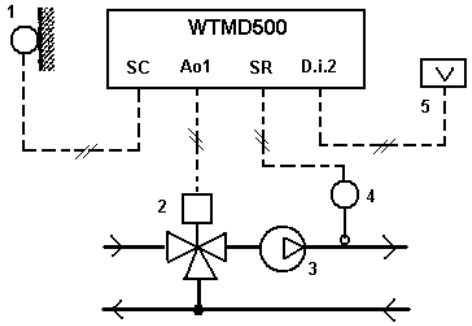
Frost protection: in case of heating fluid lack or of faulty control, if the anti-frost thermostat (5) detects a temperature lower than the set value, the controller stops the fan and closes the outside air damper.

Frost protection: in case of heating fluid lack or of faulty control, if the anti-frost thermostat (5) detects a temperature lower than the set value, the controller stops the fan and closes the outside air damper.

Possible Variants:

- - fan control on exhaust on digital output **Rel2** with switch-on delay with respect to the supply fan
- remote set point of the heating coil on **SC** input, or compensated outside set point.

EXAMPLE 4:
HOT/COLD WATER PLANT IN WITH S/W CHANGEOVER

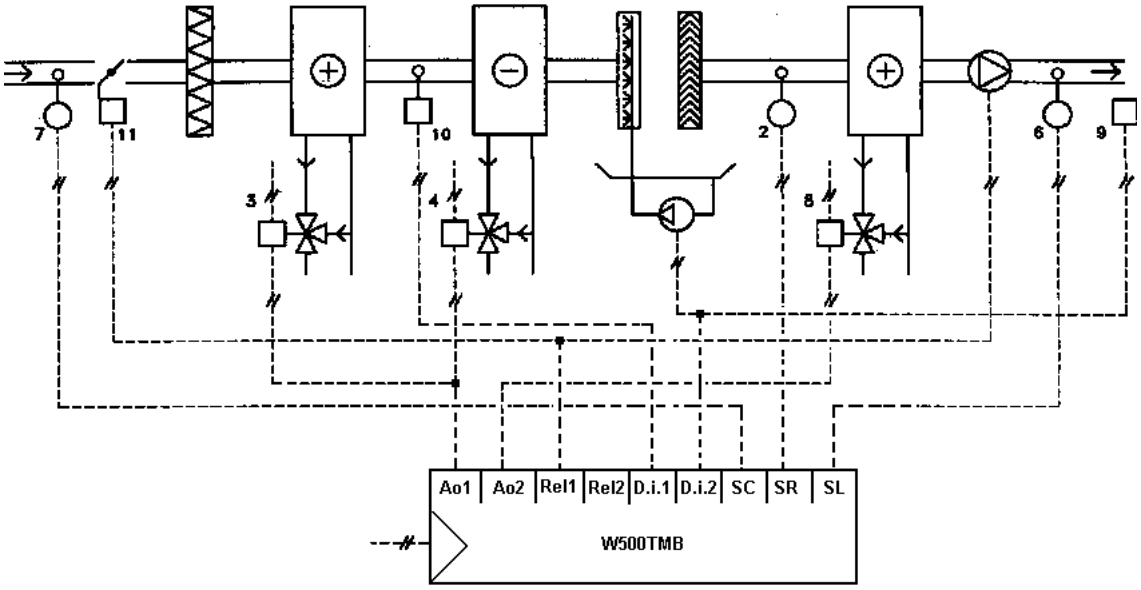


OPERATION

The circuit is supplied by hot water in winter and cold water in summer. Through the S/W changeover switch (5), according to the season, the valve (2) is driven by the controller compensated by outside temperature in winter (1), by the fixed-point controller in summer.

Possible variants: ModBus supervision by W500TMB controller or proper additional module (BusAdapter).

EXAMPLE 5:
PRIMARY AIR PLANT WITH RE-HEAT



OPERATION

The P+I action controller carries out time control of the saturation temperature (2) compensated with the outside temperature (7), by driving in sequence the valves on pre-heat (3) and pre-cool (4) coils. The P action controller controls reheat temperature (6). The room humidistat (9) drives directly the humidifier; its action is signalled to the controller. As a variant, the humidistat can be on air exhaust duct**.** ModBus supervision is possible also displaying the on/off humidifier.

Anti-frost protection: The thermostat (10) disables the fan and, consequently, the damper actuator (11) on the outside air is closed.

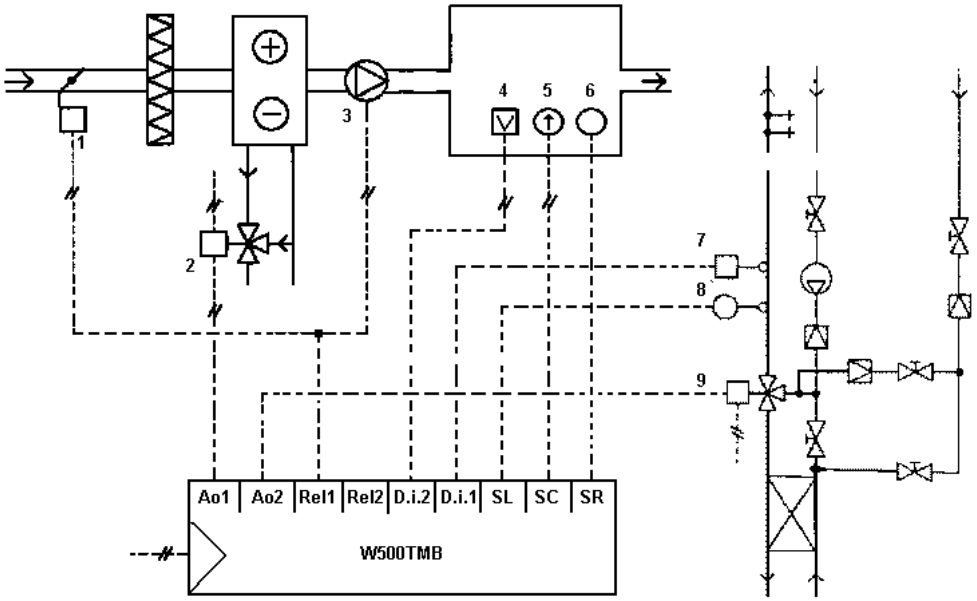
Possible variants:

- fan control on air exhaust on **Rel2** digital output with switch-on delay with respect to the supply fan **Rel1**.

Possible alternatives: Electrical mono-phase reheat coil with ON/OFF action on **Rel2**, which controls supply temperature (6).

EXAMPLE 6:

OUTSIDE AIR TIME PLANT AND WATER SERVICE CONTROL WITH RAPID EXCHANGER



OPERATION

The P+I action controller carries out time control of room temperature (6), driving the heating/cooling coil with S/W mode through changeover switch (4) and remote set through potentiometer selector (5). The P action controller maintains at the set value the water temperature detected by the sensor (8), to the user, by driving the proportional valve (9), which mixes water from the waterworks and return with the water from the exchanger. The 2-position safety thermostat (7) closes the valve, if the User temperature exceeds the set value.

Possible variants:

- fan control on air exhaust on **Rel2** digital output with switch-on delay with respect to the supply fan **Rel1**.